

# AutoRec: Autoencoders Meet Collaborative Filtering

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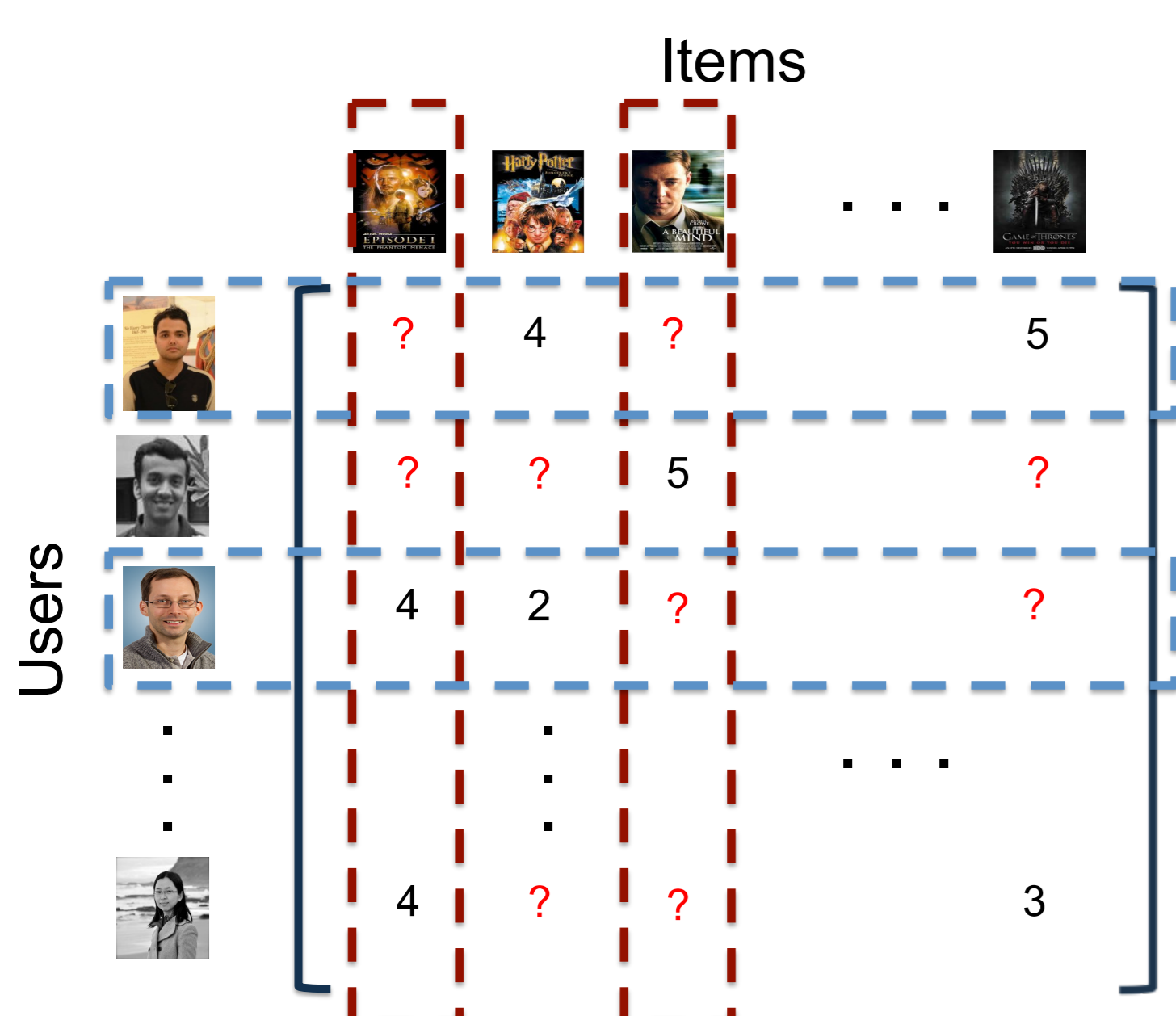


## Motivation

Autoencoders have been proven very successful in various vision and speech problems. Can we do the same for collaborative filtering?

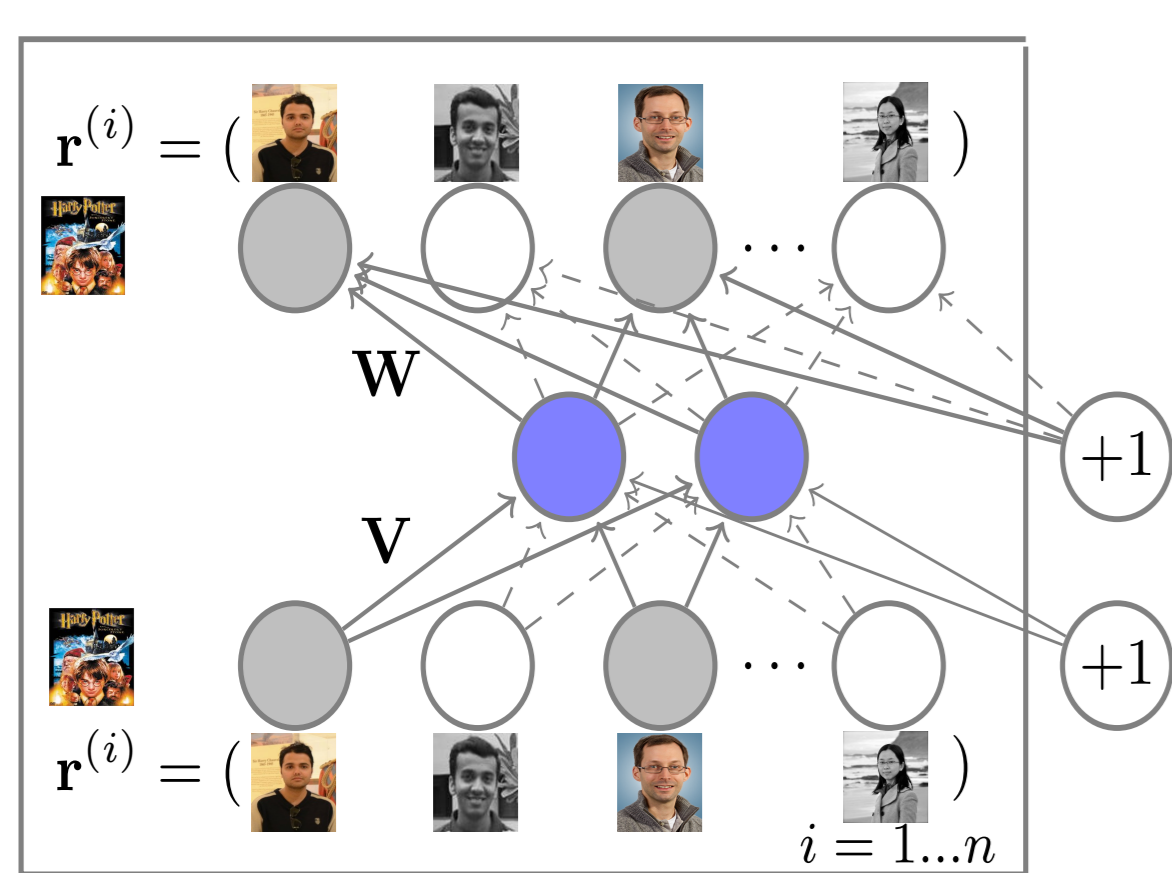
A: Yes

## Rating prediction problem



Given a **partially observed** user-item rating matrix,  $R^{m \times n}$ , fill in the missing entries

## AutoRec model



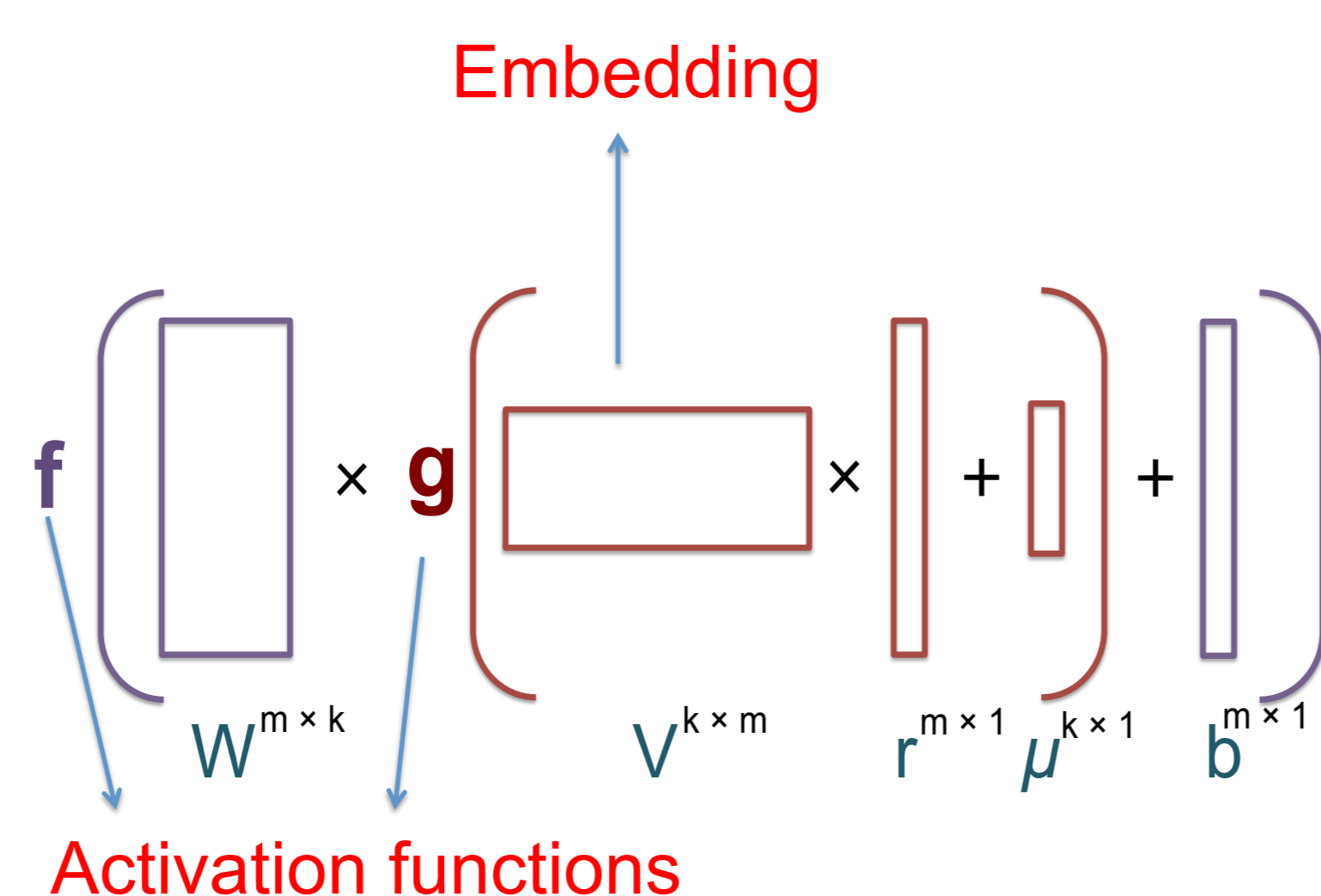
For each item, construct (partially observed) vector of ratings  $\mathbf{r}^{(i)}$

- Perform autoencoding on result, where
- **Weights are tied** across items
- Only **observed ratings** are used to update model

**Prediction:**

$$\hat{R}_{ui} = (h(\mathbf{r}^{(i)}; \hat{\theta}))_u$$

$$h(\mathbf{r}; \theta) = f(\mathbf{W} \cdot g(\mathbf{V}\mathbf{r} + \boldsymbol{\mu}) + \mathbf{b})$$



**Training objective:**

$$\min_{\theta} \sum_{i=1}^n \|\mathbf{r}^{(i)} - h(\mathbf{r}^{(i)}; \theta)\|_2^2 + \frac{\lambda}{2} \cdot (\|\mathbf{W}\|_F^2 + \|\mathbf{V}\|_F^2)$$

## Comparisons with existing methods

|              | AutoRec                        | RBM-CF                                 |
|--------------|--------------------------------|--|
| Model type   | Discriminative                 | Generative                             |
| Objective    | RMSE                           | Log-likelihood                         |
| Optimisation | Gradient-based ( <b>fast</b> ) | Contrastive divergence ( <b>slow</b> ) |
| Ratings      | Real-valued                    | Discrete                               |

|                | AutoRec    | Matrix Factorization              |
|----------------|------------|-----------------------------------|
| Embedding      | Users only | Users and items (more parameters) |
| Representation | Non-linear | Linear                            |

## Experiments

|         | Data Description |        |
|---------|------------------|--------|
|         | #users           | #items |
| ML-1M   | 6,040            | 3,706  |
| ML-10M  | 69,878           | 10,677 |
| Netflix | 480,189          | 17,770 |

Q: Is user- or item-based modelling better?

A: **Item-based** is superior.

|           | ML-1M        | ML-10M       |
|-----------|--------------|--------------|
| U-RBM     | 0.881        | 0.823        |
| I-RBM     | 0.854        | 0.825        |
| U-AutoRec | 0.874        | 0.867        |
| I-AutoRec | <b>0.831</b> | <b>0.782</b> |

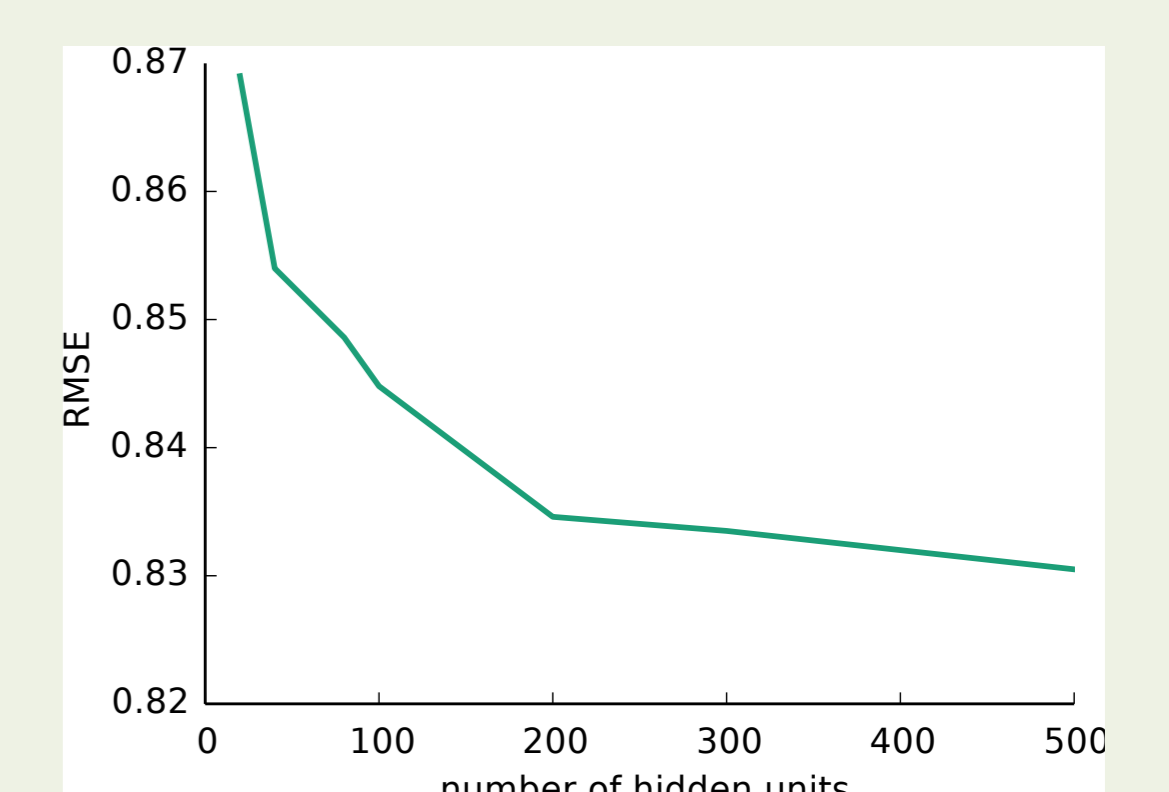
Q: What are good choices of activations  $f(\cdot)$ ,  $g(\cdot)$ ?

A: **Nonlinearity** in hidden unit is key for performance

|          | $f(\cdot)$ | $g(\cdot)$ | RMSE         |
|----------|------------|------------|--------------|
| Identity | Identity   | Identity   | 0.872        |
| Sigmoid  | Identity   | Identity   | 0.852        |
| Identity | Sigmoid    | Sigmoid    | <b>0.831</b> |
| Sigmoid  | Sigmoid    | Sigmoid    | 0.836        |

Q: How many hidden units are needed for AutoRec?

A: Good performance with **~400 hidden units**



Q: How does AutoRec perform against all baselines?

A: **Systematically outperforms** state-of-the-art methods

|           | ML-1M        | ML-10M       | Netflix      |
|-----------|--------------|--------------|--------------|
| BiasedMF  | 0.845        | 0.803        | 0.844        |
| I-RBM     | 0.854        | 0.825        | -            |
| U-RBM     | 0.881        | 0.823        | 0.845        |
| LLORMA    | 0.833        | <b>0.782</b> | 0.834        |
| I-AutoRec | <b>0.831</b> | <b>0.782</b> | <b>0.823</b> |

Q: Do deep extensions of AutoRec help?

A: Deep I-AutoRec with three hidden layers (500-200-500) reduced RMSE from 0.831 to 0.827 on ML-1M dataset.

Try it now: <https://github.com/mesuvash/NNRec>

## Future work

Further exploration of **deep autoencoders**, and applications to **implicit feedback** datasets.

## References

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